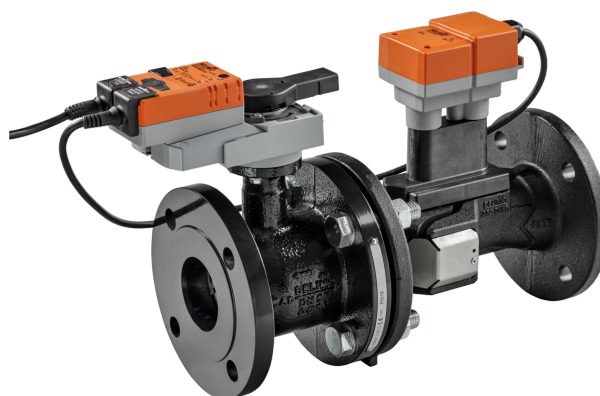


Characterised control valve with sensor-operated flow control, 2-way, Flange, PN 16 (EPIV)

- Nominal voltage AC/DC 24 V
- Control modulating, communicative
- For closed water systems
- For modulating control of air-handling and heating systems on the water side
- Communication via Belimo MP-Bus or conventional control
- Conversion of active sensor signals and switching contacts



Picture may differ from product



Type Overview

Type	DN	V'nom [l/s]	V'nom [l/min]	V'nom [m³/h]	Kvs theor. [m³/h]	PN
EP065F+MP	65	8	480	28.8	50	16
EP080F+MP	80	11	660	39.6	75	16
EP100F+MP	100	20	1200	72	127	16
EP125F+MP	125	31	1860	111.6	195	16
EP150F+MP	150	45	2700	162	254	16

Kvs theor.: theoretical Kvs value for pressure drop calculation

Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	6 W (DN 65, 80) 9 W (DN 100, 125, 150)
	Power consumption in rest position	4.5 W (DN 65, 80) 6 W (DN 100, 125, 150)
	Power consumption for wire sizing	10 VA (DN 65, 80) 12 VA (DN 100, 125, 150)
	Connection supply / control	Cable 1 m, 4x 0.75 mm²
	Parallel operation	Yes (note the performance data)
Data bus communication	Communicative control	MP-Bus
	Number of nodes	MP-Bus max. 8
Functional data	Operating range Y	2...10 V
	Input impedance	100 kΩ
	Operating range Y variable	Start point 0.5...24 V End point 8.5...32 V
	Operating modes optional	Modulating (DC 0...32 V)
	Position feedback U	2...10 V
	Position feedback U note	Max. 1 mA
	Position feedback U variable	Start point 0.5...8 V End point 2...10 V
	Sound power level motor	45 dB(A)
	V'max adjustable	30...100% of V'nom
	Control accuracy	±5% (of 25...100% V'nom) @ 20°C / Glycol 0% vol.

Technical data

Functional data	Control accuracy note	±10% (of 25...100% V'nom) @ -10...120°C / Glycol 0...50% vol.
	Min. controllable flow	1% of V'nom
	Fluid	Water, water with glycol up to max. 50% vol.
	Fluid temperature	-10...120°C [14...248°F]
	Close-off pressure Δps	690 kPa
	Differential pressure Δpmax	340 kPa
	Flow characteristic	equal percentage (VDI/VDE 2173), optimised in the opening range
	Flow characteristic note	switchable to linear (VDI/VDE 2173)
	Leakage rate	air-bubble tight, leakage rate A (EN 12266-1)
	Pipe connection	Flange according to EN 1092-2
	Installation orientation	upright to horizontal (in relation to the spindle)
	Servicing	maintenance-free
	Manual override	with push-button, can be locked
Flow measurement	Measuring principle	Ultrasonic flow measurement
	Measuring accuracy flow	±2% (of 25...100% V'nom) @ 20°C / glycol 0% vol.
	Measuring accuracy flow note	±6% (of 25...100% V'nom) @ -10...120°C / glycol 0...50% vol.
	Min. flow measurement	0.5% of V'nom
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)
	Degree of protection IEC/EN	IP54
	Pressure equipment directive	CE according to 2014/68/EU
	EMC	CE according to 2014/30/EU
	Type of action	Type 1
	Rated impulse voltage supply / control	0.8 kV
	Pollution degree	3
	Ambient humidity	Max. 95% RH, non-condensing
	Ambient temperature	-30...50°C [-22...122°F]
Materials	Storage temperature	-20...80°C [-4...176°F]
	Valve body	EN-GJL-250 (GG 25)
	Flow measuring pipe	EN-GJL-250 (GG 25), with protective paint
	Closing element	Stainless steel AISI 316
	Spindle	Stainless steel AISI 304
	Spindle seal	EPDM
	Seat	PTFE, O-ring Viton

Safety notes

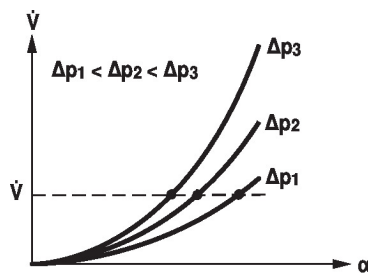


- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

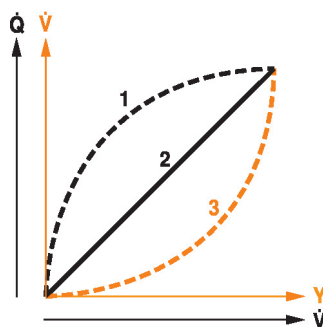
Operating mode The HVAC performance device is comprised of three components: characterised control valve (CCV), measuring pipe with flow sensor and the actuator itself. The adjusted maximum flow ($V'max$) is assigned to the maximum control signal (typically 10 V / 100%). The HVAC performance device can be controlled via communicative or analogue signals. The fluid is detected by the sensor in the measuring pipe and is applied as the flow value. The measured value is balanced with the setpoint. The actuator corrects the deviation by changing the valve position. The angle of rotation α varies according to the differential pressure through the control element (see flow curves).

Flow rate curves



Transmission behaviour HE Heat exchanger transmission behaviour

Depending on the construction, temperature spread, fluid characteristics and hydronic circuit, the power Q is not proportional to the water volumetric flow V' (Curve 1). With the classical type of temperature control, an attempt is made to maintain the control signal Y proportional to the power Q (Curve 2). This is achieved by means of an equal-percentage flow characteristic (Curve 3).



Control characteristics

The fluid velocity is measured in the measuring component (sensor electronics) and converted to a flow rate signal.

The control signal Y corresponds to the power Q via the exchanger, the flow is controlled in the EPIV. The control signal Y is converted into an equal-percentage characteristic curve and provided with the V'max value as the new reference variable w. The momentary control deviation forms the control signal Y1 for the actuator.

The specially configured control parameters in connection with the precise flow rate sensor ensure a stable quality of control. They are, however, not suitable for rapid control processes, such as domestic water control. U5 displays the measured flow as voltage (factory setting).

Configuring V'max with ZTH EU:

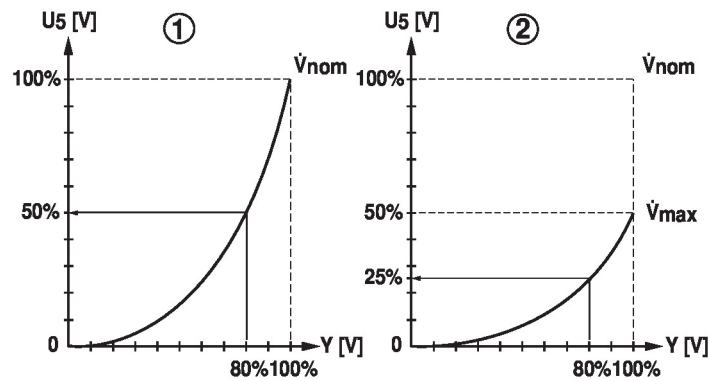
U5 refers to the respective V'nom, i.e. if V'max is e.g. 50% of V'nom, then Y = 10 V, U5 = 5 V.

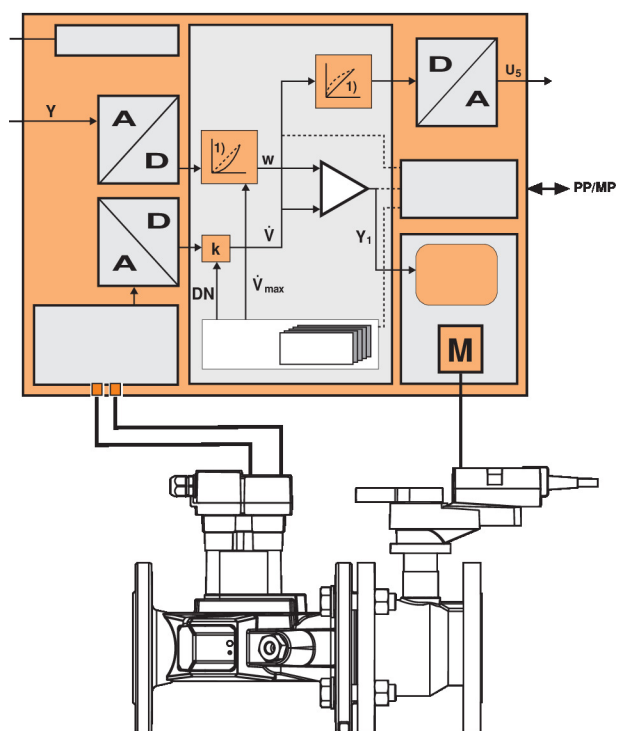
Configuring V'max with PC-Tool:

In the PC-Tool, the maximum flow rate to which U5 refers can be set individually. If V'max is changed (e.g. to 70% V'nom), the U5 flow range is also automatically changed to the same value (e.g. 70% V'nom: U5 = 10 V). This adjustment can be reversed by entering a value manually (U5 flow range = 100%: U5 refers to V'nom).

As an alternative, U5 can be used to display the valve opening angle.

1. Standard equal percentage V'max = V'nom / 2. effect V'max < V'nom

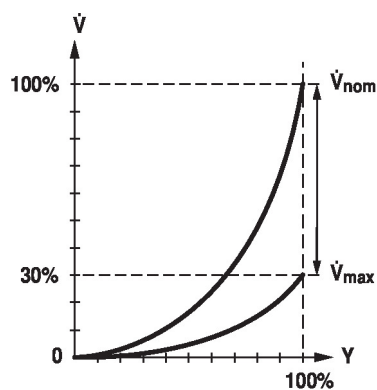




Flow control

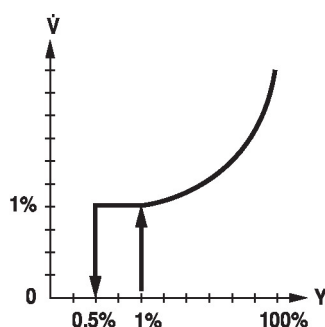
V_{nom} is the maximum possible flow.

V_{max} is the maximum flow rate which has been set with the highest control signal. V_{max} can be set between 30% and 100% of V_{nom} .



Product features

- Creep flow suppression** Given the very low flow speed in the opening point, this can no longer be measured by the sensor within the required tolerance. This range is overridden electronically.
- Opening valve**
The valve remains closed until the flow required by the control signal DDC corresponds to 1% of V'nom. The control along the flow characteristic is active after this value has been exceeded.
- Closing valve**
The control along the flow characteristic is active up to the required flow rate of 1% of V'nom. Once the level falls below this value, the flow rate is maintained at 1% of V'nom. If the level falls below the flow rate of 0.5% of V'nom required by the control signal DDC, then the valve will close.



- Converter for sensors** Connection option for a sensor (active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.
- Configurable device** The factory settings cover the most common applications. Single parameters can be modified with Belimo Assistant 2 or ZTH EU.
- Control signal inversion** This can be inverted in cases of control with an analogue control signal. The inversion causes the reversal of the standard behaviour, i.e. at a control signal of 0%, regulation is to V'max, and the valve is closed at a control signal of 100%.
- Hydronic balancing** With the Belimo tools, the maximum flow rate (equivalent to 100% requirement) can be adjusted on-site, simply and reliably, in a few steps. If the device is integrated in the management system, then the balancing can be handled directly by the management system.
- Manual override** Manual override with push-button possible (the gear train is disengaged for as long as the button is pressed or remains locked).
- High functional safety** The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Accessories

Tools	Description	Type
	Service tool for wired and wireless setup, on-site operation and troubleshooting.	Belimo Assistant 2
	Adapter for Service-Tool ZTH	MFT-C
	Connecting cable 5 m, A: RJ11 6/4 LINK.10, B: 6-pin for connection to service socket	ZK1-GEN
	Connecting cable 5 m, A: RJ11 6/4 LINK.10, B: free wire end for connection to MP/PP terminal	ZK2-GEN
	Belimo Assistant Link Bluetooth and USB to NFC and MP-Bus converter for configurable and communicative devices	LINK.10
Electrical accessories	Description	Type
	Stem heater flange F05 (30 W)	ZR24-F05

Accessories

	Description	Type
	MP-Bus power supply for MP actuators	ZN230-24MP
Gateways	Description	Type
	Gateway MP to BACnet MS/TP	UK24BAC
	Gateway MP to Modbus RTU	UK24MOD

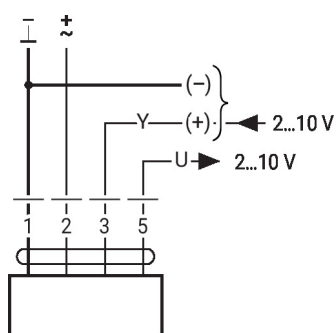
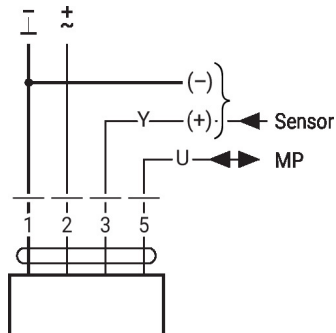
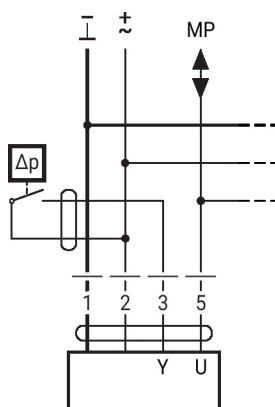
Electrical installation


Supply from isolating transformer.

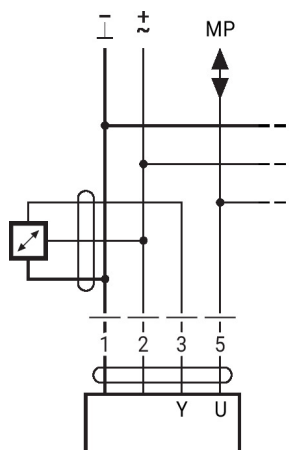
Parallel connection of other actuators possible. Observe the performance data.

Wire colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

AC/DC 24 V, modulating

MP-Bus

Converter for sensors
Connection of external switching contact


- Switching current 16 mA @ 24 V
- Start point of the operating range must be configured on the MP actuator as ≥ 0.5 V

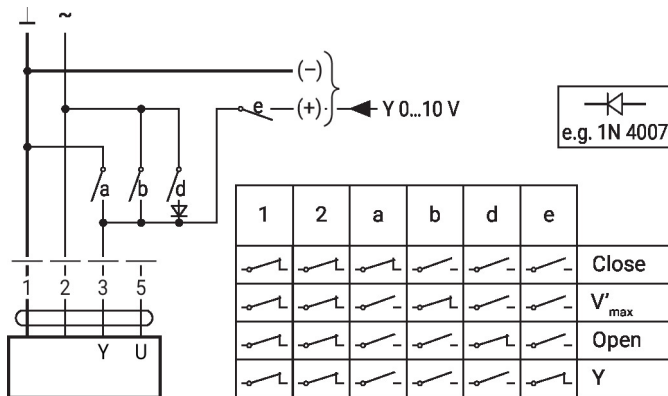
Connection of active sensors


- Supply AC/DC 24 V
- Output signal 0...10 V (max. 0...32 V)
- Resolution 30 mV

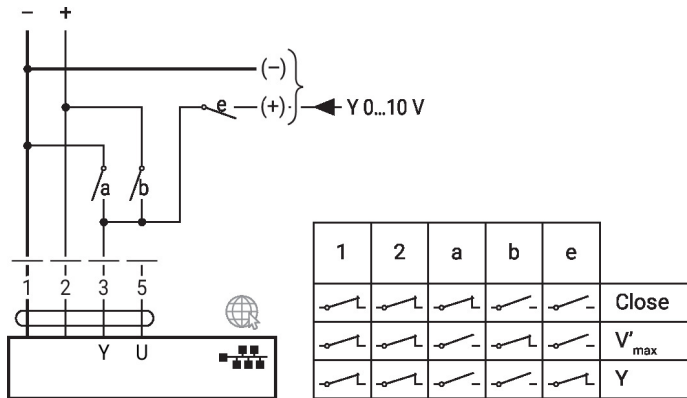
Further electrical installations

Functions with specific parameters (configuration necessary)

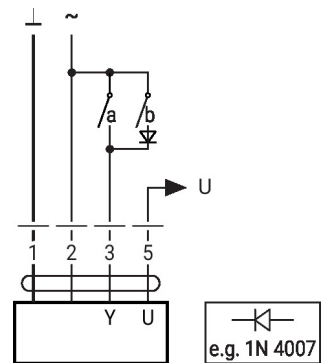
Override control and limiting with AC 24 V with relay contacts



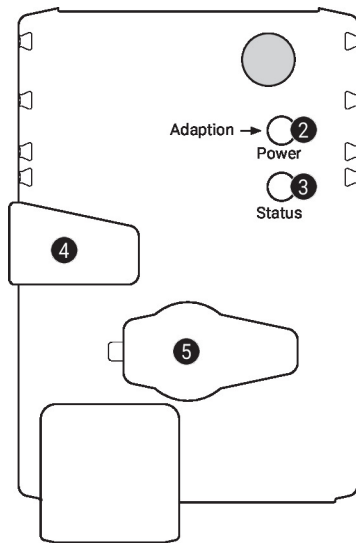
Override control and limiting with DC 24 V with relay contacts



Control 3-point



Operating controls and indicators



2 Push-button and LED display green

Off: No power supply or malfunction

On: In operation

Press button: Triggers angle-of-rotation adaptation, followed by standard mode

3 Push-button and LED display yellow

Off: Standard mode

On: Adaptation or synchronisation process active

Flickering: MP-Bus communication active

Press button: Confirmation of the addressing

4 Manual override button

Press button: Gear train disengages, motor stops, manual override possible

Release button: Gear train engages, standard mode

5 Service plug

For connecting configuration and service tools

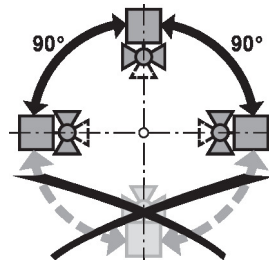
Check power supply connection

2 Off and 3 On Possible wiring error in power supply

Installation notes

Permissible installation orientation

The ball valve can be installed upright to horizontal. The ball valve may not be installed in a hanging position, i.e. with the spindle pointing downwards.



Installation location in return

Installation in the return is recommended.

Water quality requirements

The water quality requirements specified in VDI 2035 must be adhered to.

Belimo valves are regulating devices. For the valves to function correctly in the long term, they must be kept free from particle debris (e.g. welding beads during installation work). The installation of a suitable strainer is recommended.

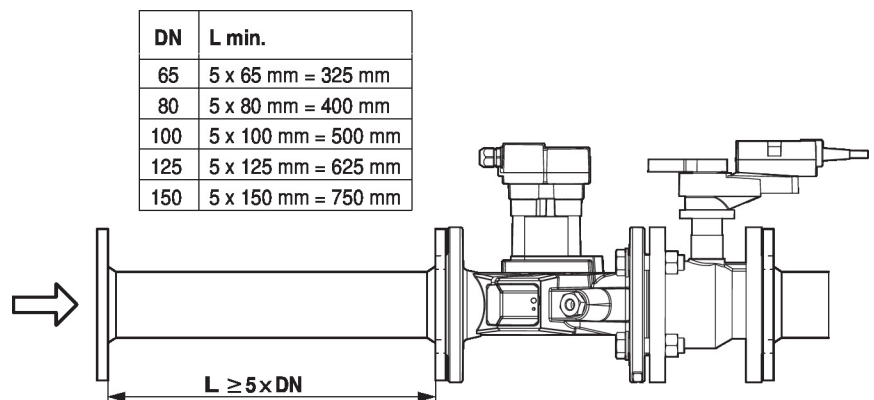
The water must exhibit a conductivity $\geq 20 \mu\text{S}/\text{cm}$ during operation for correct functioning. It should be noted that, under normal circumstances, even filling water with a lower conductivity will experience an elevation of its conductivity to above the minimum required value during filling and that the system can thus be put into operation.

Elevation of conductivity during filling caused by:

- untreated residual water from pressure test or pre-rinsing
- metal salts (e.g. surface rust) dissolved out of the raw material

Installation notes

- Spindle heater** In cold water applications and warm humid ambient air, condensation can be caused in the actuators. This can lead to corrosion in the gear train of the actuator and a breakdown of the actuator. In such applications, the use of a spindle heater is recommended.
The spindle heater must only be activated when the system is in operation because it does not have a temperature controller.
- Servicing** Ball valves, rotary actuators and sensors are maintenance-free.
Before any service work on the control element is carried out, it is essential to isolate the rotary actuator from the power supply (by unplugging the electrical cable if necessary). Any pumps in the part of the piping system concerned must also be switched off and the appropriate slide valves closed (allow all components to cool down first if necessary and always reduce the system pressure to ambient pressure level).
The system must not be returned to service until the ball valve and the rotary actuator have been correctly reassembled in accordance with the instructions and the pipeline has been refilled by professionally trained personnel.
- Flow direction** The direction of flow, specified by an arrow on the housing, is to be complied with, since otherwise the flow rate will be measured incorrectly.
- Inlet section** A flow calming section or inlet section in the direction of flow must be maintained in front of the flow sensor to achieve the specified measuring accuracy. Its dimensions should be at least 5x DN.



- Split installation** The valve-actuator combination may be mounted separately from the flow sensor. The direction of flow of both components must be observed.

General notes

- Valve selection** The valve is determined using the maximum required flow rate V'_{max} .
A calculation of the Kvs value is not required.
 $V'_{max} = 30 \dots 100\%$ of V'_{nom}
If no hydronic data is available, the same valve DN can be selected as the heat exchanger nominal diameter.

General notes
Minimum differential pressure (pressure drop)

The minimum required differential pressure (pressure drop through the valve) for achieving the desired flow V'max can be calculated with the aid of the theoretical Kvs value (see type overview) and the below-mentioned formula. The calculated value is dependent on the required maximum flow V'max. Higher differential pressures are compensated for automatically by the valve.

Formula

$$\Delta p_{\min} = 100 \times \left(\frac{V'_{\max}}{K_{vs \text{ theor.}}} \right)^2$$

Δp_{\min} : kPa
 V'_{\max} : m³/h
 $K_{vs \text{ theor.}}$: m³/h

Example (DN 100 with the desired maximum flow rate = 50% V'nom)

EP100F+MP

$K_{vs \text{ theor.}} = 127 \text{ m}^3/\text{h}$

$V'_{\text{nom}} = 1200 \text{ l/min}$

$50\% \times 1200 \text{ l/min} = 600 \text{ l/min} = 36 \text{ m}^3/\text{h}$

$$\Delta p_{\min} = 100 \times \left(\frac{V'_{\max}}{K_{vs \text{ theor.}}} \right)^2 = 100 \times \left(\frac{36 \text{ m}^3/\text{h}}{127 \text{ m}^3/\text{h}} \right)^2 = 8 \text{ kPa}$$

Behaviour in case of sensor failure

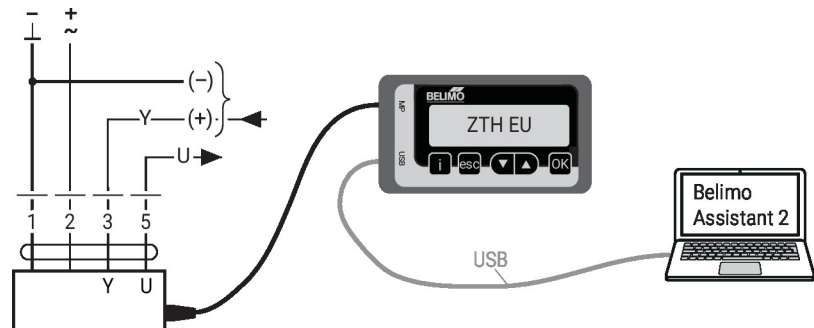
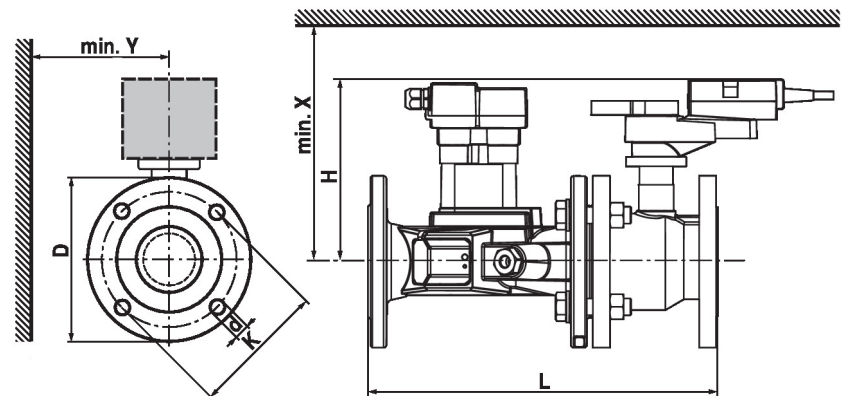
In case of a flow sensor error, the EPIV will switch from flow control to position control. Once the error disappears, the EPIV will switch back to the normal control setting.

Service
Wired connection

The device can be configured by ZTH EU via the service socket.


For an extended configuration, Belimo Assistant 2 can be connected.

Connection ZTH EU / Belimo Assistant 2


Dimensions


If $Y < 180 \text{ mm}$, the extension of the hand crank must be demounted as necessary.

Dimensions

Type	DN	L [mm]	H [mm]	D [mm]	d [mm]	K [mm]	X [mm]	Y [mm]	 kg
EP065F+MP	65	379	197	185	4 x 19	145	220	150	25
EP080F+MP	80	430	197	200	8 x 19	160	220	160	31
EP100F+MP	100	474	221	229	8 x 19	180	240	175	45
EP125F+MP	125	579	240	252	8 x 19	210	260	190	61
EP150F+MP	150	651	240	282	8 x 23	240	260	200	73

Further documentation

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology
- General notes for project planning
- Quick Guide – Belimo Assistant 2